

Preliminary Examination in Numerical Analysis

June 9, 2003

Instructions:

1. The examination is for 3 hours.
2. The examination consists of two parts:
Part I: Matrix Theory and Numerical Linear Algebra
Part II: Numerical Analysis
3. There are three problem sets in each part. **Work two out of the three problem sets for each part.**
4. All problems carry equal weights.

PART I - Matrix Theory and Numerical Linear Algebra
(Work two of the three problems in this part)

Problem 1.

- (a) Assume that A and $A + \delta A$ are $n \times n$ invertible matrices and $\eta \equiv \kappa(A) \frac{\|\delta A\|}{\|A\|} < 1$. If $Ax = b$ and $(A + \delta A)\hat{x} = b + \delta b$, prove that

$$\frac{\|x - \hat{x}\|}{\|x\|} \leq \frac{\kappa(A)}{1 - \eta} \left(\frac{\|\delta A\|}{\|A\|} + \frac{\|\delta b\|}{\|b\|} \right)$$

where $\|\cdot\|$ is any matrix operator norm and $\kappa(A)$ is the condition number of A .
 (You may use without proof that $\|(I - X)^{-1}\| \leq (1 - \|X\|)^{-1}$ if $\|X\| < 1$.)

- (b) Let U be an $n \times n$ upper triangular matrix and consider solving $Ux = b$ by backward substitution in a floating point arithmetic. Prove that the computed solution \hat{x} satisfies $(U + \delta U)\hat{x} = b$ with $|\delta U| \leq n\epsilon|U| + O(\epsilon^2)$, where ϵ is the machine precision.
 (You may use $fl(\sum_{i=1}^d x_i y_i) = \sum_{i=1}^d x_i y_i (1 + \delta_i)$ with $|\delta_i| \leq d\epsilon + O(\epsilon^2)$.)

Problem 2.

- (a) State the power method for computing the largest eigenvalue (in absolute value) of a matrix A . State and prove the convergence result for the case that A is symmetric.
- (b) For $A = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$ and $x_0 = \begin{pmatrix} 1 \\ a \end{pmatrix}$, find the sequence generated by the power method for A with x_0 as the initial vector. Discuss the convergence property of the sequence obtained. Is there any contradiction to the result in (a)? Explain.
- (c) Write down the shifted QR algorithm for a matrix A . Prove that the matrices produced are all similar to the original matrix.

Problem 3.

- (a) Describe an algorithm to compute a QR factorization of an $m \times n$ matrix A .
- (b) Let $A \in R^{m \times n}$ and $b \in R^m$ ($m \geq n$). Consider the least squares problem

$$\min_{x \in R^n} \|Ax - b\|_2. \tag{1}$$

1. Prove that if x satisfies $A^T Ax = A^T b$, then x is a solution to (??).
2. Derive a method to solve (??) via A 's singular value decomposition

$$A = U \Sigma V^T = U \begin{pmatrix} \Sigma_1 & 0 \\ 0 & 0 \end{pmatrix} V^T$$

where Σ_1 is $k \times k$.

Part II – Numerical Analysis
(Work two of the three problems in this part)

Problem 4. Suppose $g(x)$ is a C^1 function with a fixed point z , i. e. $g(z) = z$, and

$$|g'(z)| = \alpha < 1$$

(a) Prove that a fixed point iteration will converge linearly to z from any point x_0 sufficiently close to z .

(b) What is the rate of convergence ?

(c) Perform one iteration of Newton's method on the system:

$$\begin{aligned}x_1^2 - 2x_1 - x_2 + 0.5 &= 0 \\x_1^2 + 4x_2^2 - 4 &= 0\end{aligned}$$

starting at point $(2, 0.25)$.

Problem 5. Outline the ideas and steps to derive a Gauss Formula

$$\int_{-1}^1 f(x)dx = \sum_{i=0}^n A_i w_i f(x_i)$$

which is exact for all the polynomials of degree ≤ 3 on $[-1, 1]$.

(a) How many nodes (minimum number) are needed for Gauss Formula to be exact for all the polynomials of degree ≤ 3 , i.e., what is n ? and why?

(b) Use a theorem about orthogonal polynomials and the fact that $1, x, x^2 - \frac{1}{3}, x^3 - \frac{3}{5}x$ are orthogonal on $[-1, 1]$ with weight function $w_i = 1$ to determine x_i .

(c) Use method of undetermined coefficient to find A_i and write the Gauss Formula.

Problem 6. Where $x'(t) = f(t, x)$, $x(0) = x_0$ and $f_n = f(t_n, x_n)$, the formula

$$x_{n+1} - (1 - c)x_n - cx_{n-1} = \frac{h}{12}[(5 - c)f_{n+1} + 8(1 + c)f_n + (5c - 1)f_{n-1}]$$

is known to be exact for all polynomials of degree m or less for all c .

(a) Determine c so that it will be exact for all polynomials of degree $m + 1$. Find c and m .

(b) Using the c found in (a), is this method stable? strongly stable? is this method consistent? convergent?