

Lecture 39

Dec 5

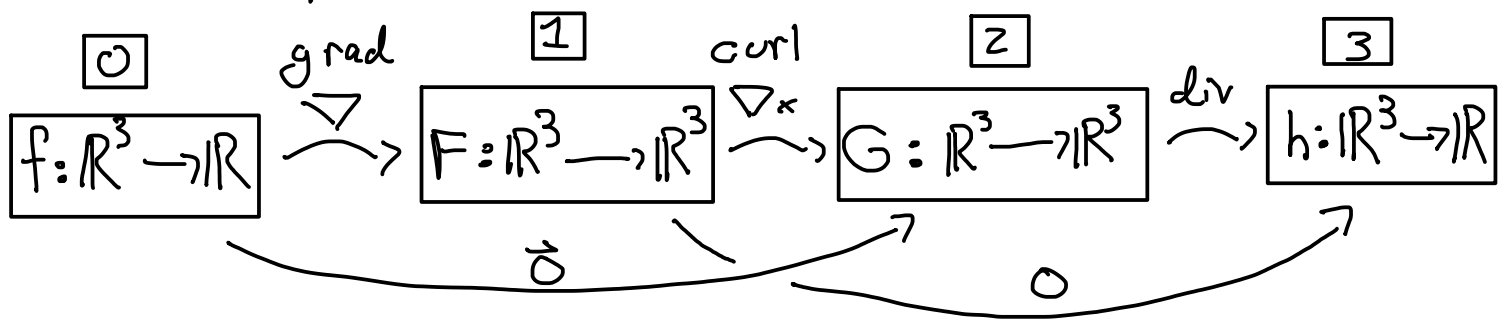
2011

(1)

This week usual tutoring hours M-Thur

Also Fri & Mon Dec 12 10AM-2PM 159 Altgeld

In summary:



If $\nabla \times \vec{F} = 0$, $\vec{F} = \nabla f$ some f

If $\text{div } \vec{G} = 0$ $\vec{G} = \nabla \times \vec{F}$ some $\vec{F}$.

called an
exact sequence

No longer "exact" if change domain.

Ex $\vec{G}: \mathbb{R}^3 \setminus \{\vec{0}\} \rightarrow \mathbb{R}^3$

$$\vec{G}(x, y, z) = \frac{1}{\rho^3} (x, y, z)$$

$$\rho = \sqrt{x^2 + y^2 + z^2}$$

$$\text{Then } \frac{\partial}{\partial x} \frac{x}{\rho^3} = \frac{\rho^3 - x^3 \rho^2 \frac{2x}{2\rho}}{\rho^6} = \frac{\rho^2 - 3x^2}{\rho^5}$$

$$\frac{\partial}{\partial x} \frac{x}{\rho^3} + \frac{\partial}{\partial y} \frac{y}{\rho^3} + \frac{\partial}{\partial z} \frac{z}{\rho^3} = \frac{3\rho^2 - 3[x^2 + y^2 + z^2]}{\rho^5} = 0.$$

So $\text{div } \vec{G} = 0$. But $\vec{G} \neq \nabla \times \vec{F}$.

S_1 = unit sphere Note $\rho = 1$ on S_1 .

$$\iint_{S_1} \frac{1}{\rho^3} (x, y, z) \cdot d\vec{S} = \iint_{S_1} 1 \, dS = 4\pi.$$

By Stokes, if $\vec{G} = \nabla \times \vec{F}$, then $\oint_{S_1} \vec{G} \cdot d\vec{S}$ should be 0 (2)
since S_1 has empty boundary.

So for domain $\mathbb{R}^3 \setminus \{0\}$, the sequence is not "exact"
at position [2].

Since $\mathbb{R}^3 \setminus \{0\}$ is simply-connected, it is still "exact"
at position [1].

Ex Similarly, define $\vec{F} : \mathbb{R}^3 \setminus z\text{-axis} \rightarrow \mathbb{R}^3$
$$\vec{F}(x, y, z) = \frac{1}{x^2 + y^2} (-y, x, 0).$$

Saw previously that $\nabla \times \vec{F} = \vec{0}$ but $\vec{F}$ is
not conservative, since

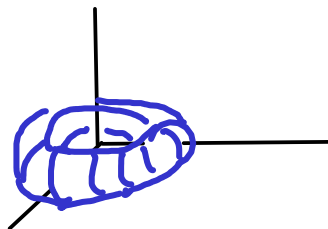
$$\oint_C \vec{F} \cdot d\vec{r} = 2\pi \neq 0.$$

unit circle. So the sequence is not "exact" at
position [1].

It turns out it is exact at position [2].

Ex Torus $(r-z)^2 + z^2 = 1$

Not exact at position [1] or [2].



Again, $\vec{F} = \frac{1}{rz} (-y, x, 0)$ defined on T , $\nabla \times \vec{F} = \vec{0}$
but $\vec{F}$ not conservative.

~~~~~  
Can say more?

For  $\mathbb{R}^3 \setminus z\text{-axis}$ , the only fields  $\vec{F}$  satisfying  $\nabla \times \vec{F} = \vec{0}$ ,  $\vec{F}$  not conservative are

$$\vec{F} = \frac{\text{constant } c}{x^2 + y^2} (-y, x, 0).$$

For  $\mathbb{R}^3 \setminus z\text{-axis}$  and line  $x=1, y=0$  the only such fields are  $\vec{F}_1 = \frac{c}{x^2 + y^2} (-y, x, 0)$

and  $\vec{F}_2 = \frac{d}{(x-1)^2 + y^2} (-y, x-1, 0)$

or any combinations of  $\vec{F}_1, \vec{F}_2$ .

Moral: The grad-curl-div sequence knows about the "shape" of the domain.

The general Stokes theorem.

Terminology

- "0-form" = function
- "1-form" something like  $f dx - g dz$  or  $ds$
- "2-form" something like  $f dx dy + g dy dz$  or  $dA$  or  $dS$
- "3-form" something like  $f dx dy dz$  or  $dV$

"differential forms"

There are operators ("the differential")

$$\{0\text{-forms}\} \xrightarrow{d^0} \{1\text{-forms}\} \xrightarrow{d^1} \{2\text{-forms}\} \xrightarrow{d^2} \{3\text{-forms}\}$$

$\xrightarrow{0} \quad \quad \quad \xrightarrow{0}$

(4)

defined as follows

$$d^0(f) = \frac{\partial f}{\partial x} dx + \frac{\partial f}{\partial y} dy + \frac{\partial f}{\partial z} dz$$

$$= \nabla(f) \cdot (dx, dy, dz).$$

$$d^1(f dx_i) = \frac{\partial f}{\partial x} dx dx_i + \frac{\partial f}{\partial y} dy dx_i + \frac{\partial f}{\partial z} dz dx_i$$

$$d^2(f dx_i dx_j) = \frac{\partial f}{\partial x} dx dx_i dx_j + \dots + \frac{\partial f}{\partial z} dz dx_i dx_j.$$

where 1) each  $dx_i$  is linear

$$2) dx_i dx_j = -dx_j dx_i$$

$$3) dx dx = 0.$$

Thm (General Stokes) Many nice region ("manifold")  
 $\omega$  (omega) any diff. form.

$$\text{Then } \sum_M d\omega = \sum_{\partial M} \omega.$$

Ex Green's Thm

$$\sum_{\partial D} \vec{F} \cdot d\vec{r} = \sum_{\partial D} P dx + Q dy \stackrel{\text{Green}}{=} \iint_D \left( \frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dx dy.$$

$\omega = P dx + Q dy$ . Then

$$\begin{aligned} d\omega &= d(P dx + Q dy) = d(P dx) + d(Q dy) \\ &= \frac{\partial P}{\partial x} \underbrace{dx dx}_0 + \frac{\partial P}{\partial y} dy dx + \frac{\partial Q}{\partial x} dx dy + \frac{\partial Q}{\partial y} \underbrace{dy dy}_0 \\ &= \left( \frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dx dy \end{aligned}$$

## Ex Stokes' Thm

(5)

$$\int_{\partial S} \vec{F} \cdot d\vec{r} = \iint_S \nabla \times \vec{F} \cdot d\vec{S}$$

Here  $\omega = P dx + Q dy + R dz$

$$\begin{aligned} \text{and we find } d\omega &= \frac{\partial P}{\partial y} dy dx + \frac{\partial P}{\partial z} dz dx + \dots \\ &= \left( \frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dx dy + \left( \frac{\partial R}{\partial x} - \frac{\partial P}{\partial z} \right) dx dz \\ &\quad + \left( \frac{\partial R}{\partial y} - \frac{\partial Q}{\partial z} \right) dy dz \end{aligned}$$

Fact If  $\vec{n} = (n_1, n_2, n_3)$  is outward pointing normal,

then  $dx dy = n_3 dS$ ,  $dz dx = n_2 dS$ ,  $dy dz = n_1 dS$

$$\text{So } d\omega = (\nabla \times \vec{F}) \cdot \vec{n} dS$$

$$\underline{\text{Ex}} \text{ Div Thm} \quad \iint_{\partial E} \vec{F} \cdot \vec{n} dS = \iiint_E \text{div } \vec{F} dV$$

$$\begin{aligned} \omega = \vec{F} \cdot \vec{n} dS &= P n_1 dS + Q n_2 dS + R n_3 dS \\ &= P dy dz + Q dz dx + R dx dy \end{aligned}$$

$$\begin{aligned} \text{So } d\omega &= \frac{\partial P}{\partial x} dx dy dz + \frac{\partial Q}{\partial y} dy dz dx + \frac{\partial R}{\partial z} dz dx dy \\ &= \text{div } \vec{F} dx dy dz. \end{aligned}$$