

Lecture 40

Dec 7

159 Altyeld

2011

Tutoring Fri & Mon Dec 12 10AM-2PM

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Office Hours Fri 1-3.

Final exam cumulative. Covers everything from class, up to & including lecture 38 (not Monday's material).

In the beginning...

Ch. 12 Vectors

- Important topics
- vectors, vector addition
 - dot product $\rightsquigarrow$ norm or magnitude
 $\rightsquigarrow$ orthogonal vectors
 - cross product
 $\vec{u} \times \vec{v}$ orthog to both $\vec{u}$ & $\vec{v}$,
 $\|\vec{u} \times \vec{v}\| = \text{area parallelogram}$
 - Equation for plane: $\vec{P}$ point on plane, $\vec{n}$ normal vector
 $\vec{n} \cdot (x, y, z) = \vec{n} \cdot \vec{P}$
 - Quadric surfaces (consider cross-sections)
 - ellipsoid $\frac{x^2}{A^2} + \frac{y^2}{B^2} + \frac{z^2}{C^2} = 1$
 - (elliptic) paraboloid $\pm z = \underbrace{Ax^2 + By^2}_{\text{both} \rightarrow 0}$
 - (saddle) hyperbolic paraboloid $\pm z = \underbrace{Ax^2 - By^2}_{\text{one or two-sheeted}}$
 - hyperboloid $\frac{x^2}{A^2} + \frac{y^2}{B^2} - \frac{z^2}{C^2} = \underbrace{\pm 1}_{\text{one or two-sheeted}}$

Ch. 13 Vector functions

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- $\vec{r}: \mathbb{R} \rightarrow \mathbb{R}^3$ parametrizes curve in $\mathbb{R}^3$
- $\vec{r}(t) = (x(t), y(t), z(t))$, $\vec{r}'(t) = (x'(t), y'(t), z'(t))$

tangent vector to curve

Interpretation: $\vec{r}(t)$ = position, $\vec{r}'(t)$ = velocity,
 $\|\vec{r}'(t)\|$ = speed

- Arc length = $\int \|\vec{r}'(t)\| dt = ds$

Ch. 14 $f(x, y, z) = c$

- level sets, contour maps
- limits for $f: \mathbb{R}^3 \rightarrow \mathbb{R}$ (ϵ, δ)
 - test along curves to show limit DNE
- continuity for $f: \mathbb{R}^3 \rightarrow \mathbb{R}$ (function value = limit value)
- partial derivatives (focus on one variable, treat others as constant)
- Clairaut's theorem $\frac{\partial}{\partial x} \frac{\partial}{\partial y} f = \frac{\partial}{\partial y} \frac{\partial}{\partial x} f$

- linear approx & tangent planes
 $P = (a, b)$. $S = \text{graph of } f(x, y)$.

Tangent plane at P given by

$$z - f(P) = f_x(P)(x-a) + f_y(P)(y-b)$$

Linear approx near P

$$L(x, y) = f(P) + f_x(P)(x-a) + f_y(P)(y-b)$$

- f differentiable @ P if $\lim_{(x,y) \rightarrow P} \frac{L(x,y) - f(x,y)}{\|(x,y) - P\|} = 0$.

- f diff. as long as f_x, f_y exist & continuous

- Chain Rule $\mathbb{R}^2 \xrightarrow{uv} \mathbb{R}^3 \xrightarrow{f} \mathbb{R}$

$$\frac{\partial}{\partial u} (f \circ g) = \frac{\partial f}{\partial x} \frac{\partial g^1}{\partial u} + \frac{\partial f}{\partial y} \frac{\partial g^2}{\partial u} + \frac{\partial f}{\partial z} \frac{\partial g^3}{\partial u}$$

- Gradient $\nabla f = (f_x, f_y, f_z)$.

Interpretation: • direction of maximal increase of f

• orthogonal to level sets

gives new way $\nearrow$ to find normal vector to surface:

- write S as level set $f=c$, $\vec{n} = \nabla(f)$.

- Directional derivative: $D_{\vec{u}} f$ generalizes partial deriv

$$D_{\vec{u}} f = \nabla(f) \cdot \vec{u}$$

- critical points if f has local max/min at P , then $\nabla f(P) = \vec{0}$.

- 2nd Der Test: $f: \mathbb{R}^2 \rightarrow \mathbb{R}$ $D = \begin{vmatrix} \frac{\partial^2 f}{\partial x^2} & \frac{\partial^2 f}{\partial x \partial y} \\ \frac{\partial^2 f}{\partial y \partial x} & \frac{\partial^2 f}{\partial y^2} \end{vmatrix}$

$$\nabla f(P) = \vec{0}$$

If: $D(P) < 0$ saddle point

• $D(P) > 0$ & $\frac{\partial^2 f}{\partial x^2}(P) > 0$ local min

• $D(P) > 0$ & $\frac{\partial^2 f}{\partial x^2}(P) < 0$ local max

- Extreme Value Thm: f continuous on closed & bounded domain Ω , then f has global max/min on Ω .

- to find global max/min of f on closed, bounded Ω , use 2nd Der test on "interior" of Ω and look for max/min on boundary

- If can write boundary as level set of g , then max/min on $\partial\Omega$ satisfy

$$\nabla f(P) = \lambda \nabla(g)(P)$$

"Lagrange Multiplier"

Ch. 15 - double integral $\iint_D f \, dA$

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- Can be computed as iterated integral

$$\iint_D f \, dA = \int_c^d \int_{g_1(y)}^{g_2(y)} f \, dx \, dy$$

$y=d$
 $g_1(y) \left\{ \text{region } D \right\} g_2(y)$
 $y=c$

- "Fubini": can also be computed as $\iint_D f \, dy \, dx$ (may need to chop up D)

- interpretation: 1) average value = $\frac{1}{\text{area}(D)} \iint_D f \, dA$
 f on D

2) volume of shape w/ bottom D & height given by f

- triple integrals similar $\iiint_E f \, dV = \int_a^b \int_{g_1(y)}^{g_2(y)} \int_{h_1(y,z)}^{h_2(y,z)} f \, dx \, dy \, dz$
"slice" region E

- change of coords: polar / cylindrical, spherical

$$r \, dr \, d\theta$$

$$\rho^2 \sin \phi \, d\rho \, d\phi \, d\theta$$

- General change-of-coords

$$T(u, v, w) = (x, y, z)$$

Then, if $E = T(R)$, get

$$J_{\text{Jacobian}} = \frac{J(T)}{J(T)} = \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} & \frac{\partial x}{\partial w} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} & \frac{\partial y}{\partial w} \\ \frac{\partial z}{\partial u} & \frac{\partial z}{\partial v} & \frac{\partial z}{\partial w} \end{vmatrix}$$

$$\iiint_E f(x, y, z) \, dx \, dy \, dz$$

$$= \iiint_R f(x(u, v, w), y(u, v, w), z(u, v, w)) |J(T)| \, du \, dv \, dw$$

Ch. 16 - vector fields $\vec{F}$, $\vec{F}$ conservative if $\vec{F} = \nabla f$

- line integrals: $\int_C f \, ds = \int_a^b f(\vec{r}(t)) \|\vec{r}'(t)\| \, dt$
of functions

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- interpretation: area of curved region

- line integrals of vector fields $\int_C \vec{F} \cdot d\vec{r} = \int_a^b \vec{F}(\vec{r}(t)) \cdot \vec{r}'(t) dt$

interpretation: work

- Fundamental Theorem $\int_C \nabla f \cdot d\vec{r} = f(\vec{r}(b)) - f(\vec{r}(a))$

- 1st Recognition Theorem

$\vec{F}$ conservative $\Leftrightarrow \int_C \vec{F} \cdot d\vec{r}$ is path independent

- 2nd Recognition Theorem

$\vec{F}$ conservative on simply-connected domain $\Leftrightarrow \frac{\partial P}{\partial y} = \frac{\partial Q}{\partial x}$

- Green's thm: $\int_{\partial D} \vec{F} \cdot d\vec{r} = \iint_D \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dA$

- $\text{curl } \vec{F} = \nabla \times \vec{F}$

interpretation: points in direction of rotational axis

2nd Recognition theorem for $\vec{F}: \mathbb{R}^3 \rightarrow \mathbb{R}^3$

$\vec{F}$ conservative on simply-connected domain $\Leftrightarrow \nabla \times \vec{F} = \vec{0}$

- $\text{div } \vec{F} = \nabla \cdot \vec{F}$

interpretation: measures rate of expansion/compression

- for $\vec{F}: \mathbb{R}^3 \rightarrow \mathbb{R}^3$, $\vec{F} = \nabla \times \vec{G} \Leftrightarrow \text{div } \vec{F} = 0$.

- $\vec{r}(u,v)$ parametrizing S , then normal vector

$$\vec{n} = \vec{r}_u \times \vec{r}_v$$

- surface integral of function $\iint_S f dS = \iint_D f(x(u,v), y(u,v), z(u,v)) \|\vec{r}_u \times \vec{r}_v\| dA$

- average value of f on S = $\frac{1}{\text{area}(S)} \iint_S f \, dS$.

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- surface integral of vector field $\iint_S \vec{F} \cdot d\vec{S} = \iint_S \vec{F} \cdot \vec{n} \, dS$

$\vec{r}_u \times \vec{r}_v$
 $\downarrow$
 $\vec{n}$

interpretation: flux

- Stokes' thm $\int_{\partial S} \vec{F} \cdot d\vec{r} = \iint_S (\nabla \times \vec{F}) \cdot d\vec{S}$

(generalizes Green's thm)

- Divergence thm either $\int_{\partial S} \vec{F} \cdot \vec{n} \, dS = \iint_S \text{div } \vec{F} \, dS$

or $\iint_{\partial E} \vec{F} \cdot \vec{n} \, dS = \iiint_E \text{div } \vec{F} \, dV$